Norwegian Meteorological

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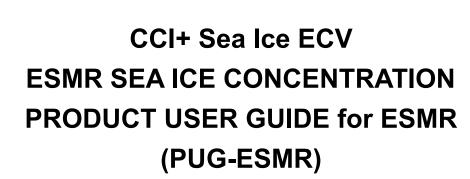


European Space Agency



ESA CCI+ CLIMATE CHANGE INITIATIVE PHASE 1: NEW R&D ON CCI ECVs

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Contents	
1 INTRODUCTION	6
1.1 Purpose	6
1.2 Scope	6
1.3 Document Status	6
1.4 Applicable Documents	6
1.5 Acronyms and Abbreviations	7
1.6 Executive Summary	9
2 The input data	10
2.1 The NIMBUS 5 ESMR TAB data and atmospheric reanalysis colocation	10
2.1.1 Satellite variables	10
2.1.2 ERA5 variables	11
3. The processing chain flow-chart	12
4. The sea ice concentration and its uncertainty	14
5. The output sea ice concentration dataset	16
5.1 The land, coast and climatological masks	16
5.2 The processing flags and land-spill over correction	16
5.3 Where to get the data?	16
References	17
Appendix A: The sea ice concentration data-set structure	18

#### **1 INTRODUCTION**

The experimental NASA NIMBUS satellite programme operating from the 1960s to the 1980s was very successful and there is heritage from it in a number of modern satellite programs. Even though the Electrically Scanning Microwave Radiometer (ESMR) onboard the NIMBUS 5 was a predecessor of modern multi-frequency radiometers there are still parts of modern processing methodologies which can be applied to the data to derive the sea ice extent globally. In fact both the dynamical tie-points and the atmospheric noise reduction of the brightness temperatures (Tb's) can reduce the noise over both ice and open water consistently. These are also the reasons for reprocessing the data which are presented in this report. The NIMBUS 5 ESMR sea ice dataset extends the sea ice climate data record with an important period in the 1970s.

#### 1.1 Purpose

This document is the ESMR PUG for sea ice concentration for the Sea Ice ECV within CCI+ PHASE 1 - NEW R&D ON CCI ECVs, which is being undertaken by a METNO-led consortium. It presents NIMBUS 5 ESMR sea ice concentration data-set covering the period between December 1972 and May 1977 with some interruptions.

#### 1.2 Scope

This document presents the processed data, the variable names and meaning in the NetCDF files and the file structure. It also presents the land-masks and the climatological masks used in the processing and the flags which are signifying the processing status. The algorithms are not part of this document, but the ATBD (Ref. 1), and the validation of the product is part of a separate report, the PVIR-ESMR (Ref. 2).

#### 1.3 Document Status

This product user guide for ESMR describes the NIMBUS 5 ESMR sea ice concentration dataset at the end of the ESA CCI+ Phase 1 project.

#### **1.4 Applicable Documents**

Table 1 below lists the Applicable Documents referred to in this document.

Document ID	Document referred to
Ref 1	The ATBD for sea ice concentration for the Sea Ice ECV within CCI+ PHASE 1 - NEW R&D ON CCI ECVs
Ref 2	The ESMR PVIR for sea ice concentration for the Sea Ice ECV within CCI+ PHASE 1 - NEW R&D ON CCI ECVs

 Table 1: Applicable Documents

## 1.5 Acronyms and Abbreviations

The table below lists the acronyms and abbreviations used in this volume.

Table 2: Acronyms and Abbreviations. Acronyms for the deliverable items (URD,
etc) and partner institutions (AWI,) are not repeated.

AOGCM A AR5, AR6 V ASAR A C3S E CCI C	Advanced Microwave Scanning Radiometer (for EOS / #2) Arctic Ocean General Climate Model WMO IPCC Assessment Report series Advanced Synthetic Aperture Radar EU Copernicus Climate Change Service Climate Change Initiative
AR5, AR6 V ASAR A C3S E CCI C	WMO IPCC Assessment Report series Advanced Synthetic Aperture Radar EU Copernicus Climate Change Service
ASAR A C3S E CCI C	Advanced Synthetic Aperture Radar EU Copernicus Climate Change Service
C3S E CCI C	EU Copernicus Climate Change Service
ССІ С	
	Climate Change Initiative
0.0.0	
CDR C	Climate Data Record
CMEMS E	EU Copernicus Marine Environment Monitoring Service
CMIP5, CMIP6 C	Coupled Model Intercomparison Project series
СМИС С	Climate Modeling User Group
CRG C	Climate Research Group
CS-2 E	ESA's CryoSat-2
DEWG C	CCI Data Engineering Working Group
EASE grid E	Equal-Area Scalable Earth Grid
ECMWF E	European Centre for Medium-Range Weather Forecasts
ECV E	Essential Climate Variable
ENVISAT E	ESA's Environmental Satellite
EO E	Earth Observation
ERS E	European Remote Sensing Satellite
ESA E	European Space Agency
ESMR E	Electrically Scanning Microwave Radiometer
EUMETSAT E	European Organization for the Exploitation of Meteorological Satellites
FoV ( <i>alt</i> FOV)  F	Field-of-View
FY3 F	<sup>-</sup> eng Yun 3
FYI F	First Year Ice
GCOS V	WMO's Global Climate Observing System
GCW V	WMO's Global Cryosphere Watch
ICDR II	nterim Climate Data Record
IMB I	ce Mass Balance buoy

D's Intergovernmental Panel on Climate Change lite data processing Level (Level-1b,) ium Resolution Imaging Spectrometer ETSAT's Polar System, EPS Second Generation inal Ice Zone erate Resolution Imaging Spectroradiometer DWave Imager (EPS-SG) D-Wave Radiation Imager (Feng Yun 3) -Year Ice onal Aeronautics and Space Administration lational Oceanic and Atmospheric Administration lational Snow and Ice Data Centre nal Estimation ation Ice Bridge ETSAT Ocean and Sea Ice Satellite Application Facility
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ETSAT Ocean and Sea Ice Satellite Application Facility
n Water Filter
ive Microwave Radiometer
ive Microwave
ar Altimeter
nd Robin Data Package
Ice Concentration
Ice Thickness
netic Aperture Radar
netic Aperture Radar (SAR) Interferometer Radar Altimeter
ice Oriented Architecture
ning Multichannel Microwave Radiometer
Moisture and Ocean Salinity
ial Sensor Microwave/Imager
ial Sensor Microwave Imager/Sounder
ard Looking Sonar
ard Looking Sonar d Meteorological Organization

### **1.6 Executive Summary**

This product user guide describes the NIMBUS 5 ESMR input data:

- The variables used in the processing of the original tape files;

- The ERA5 met variables that were added to the dataset to produce the NetCDF files in swath projection.

These are input to the sea ice concentration processing chain. The processing chain is presented at flow-chart level: the flow of data through the processes and what data is added (land and climatological masks). Next the central equations for deriving the sea ice concentration, and its uncertainties are presented briefly and then the postprocessing of the swath files is presented describing the processing status flags and giving examples of the final NetCDF file structure. The data are stored at ESA's open data portal where it can be retrieved together with the documentation.

### 2 The input data

The Electrically Scanning Microwave Radiometer (ESMR) on board the NIMBUS 5 satellite was a one channel 19.35 GHz horizontally polarized microwave radiometer operating from 11. Dec. 1972 to 16. May. 1977 (1617 days) with some interruptions. The ESMR instrument was a cross-track scanner measuring at 78 scan positions from nadir to an incidence angle of about 63 degrees perpendicular to both sides (39 scan positions to the right and left of the flight track) of the flight track. The near circular orbit height was about 1112 km with an inclination of 81 degrees. The phased array antenna size was 85.5 x 83.3 cm and the spatial resolution about 25 km at nadir increasing to about 160 x 45 km at the edges of the swath. The full swath was about 3100 km with varying incidence angle and spatial resolution giving a very good (unprecedented) daily coverage in polar regions.

After a major data gap from 3. Jun. 1975 until 25. Aug. 1975 the instrument was only operated approximately every other day. The data have recently been made available online by NASA in the format which was used for the tape archive (TAP-files).

### 2.1 The NIMBUS 5 ESMR TAB data and atmospheric reanalysis colocation

The ESMR data were retrieved from the NASA Goddard Earth Sciences Data and information services center (GES DISC) online data archive (<u>https://disc.gsfc.nasa.gov/datasets/ESMRN5L1\_001/summary</u>). The quote from the homepage is describing the data:

"ESMRN5L1 is the Nimbus-5 Electrically Scanning Microwave Radiometer (ESMR) Level 1 Calibrated Brightness Temperature product and contains calibrated radiances expressed in units of brightness temperature measured at 19.35 GHz. The data, originally written on IBM 360 machines, were recovered from magnetic tapes, also referred to as the Calibrated Brightness Temperature Tapes (CBTT). The data are archived in their original IBM binary proprietary format, also referred to as a binary TAP file."

The TAP files were read using NASA software and converted to NetCDF format. Each data point in the TAP file was matched up with ERA5 data (Hersbach et al., 2020) in time and space (nearest) and written to the NetCDF file. The data are structured line by line (across-track) retaining the original data structure and all variables. The variables are listed in section 2.1.1 and 2.1.2,

#### 2.1.1 Satellite variables

Data variables used in the processing:

Time	time of data
Brightness_temperature	Brightness temperature of the 78 scan spots
Latitude	latitude of the 78 scan spots [degrees]
Longitude	longitude of the 78 scan spots [degrees

#### 2.1.2 ERA5 variables

u10	u component of the wind speed at 10 m (parallel to longitude)
v10	v component of the wind speed at 10 m (parallel to longitude)
t2m	2 m air temperature
siconc	sea ice concentration [0,1]
sst	sea surface temperature [K]
tcw	total column water [kgm-2]
tcwv	total column water vapor [kgm-2]
era_time	valid time for analysis

# 3. The processing chain flow-chart

The processing chain flow chart is shown in Figure 1. Each of the processes are explained briefly in the figure caption and details are provided in the next section, section 4.

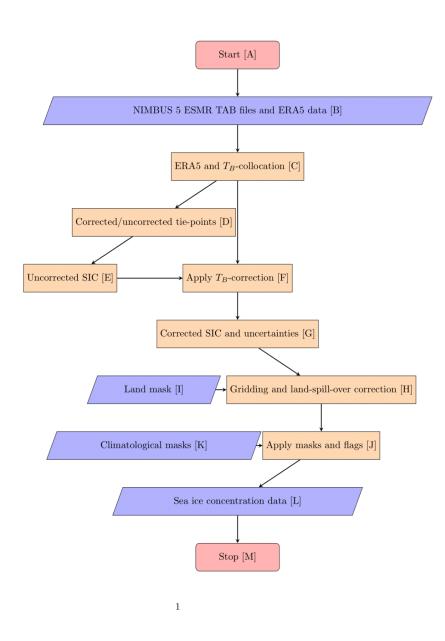


Figure 1. The ESMR sea ice concentration processing chain flow chart: A: starting the process, B: the ESMR TAB files and the ERA5 files are read and formatted, C: The ESMR

and ERA5 files are collocated to the nearest point in time and space, D: the corrected and uncorrected tie-points are derived using the ERA5 data and the radiative transfer model, E: the uncorrected SIC is derived using the tie-points, F: the Tb's are corrected using the ERA5 data, the radiative transfer model and the sea ice concentration from E, G: the sea ice concentration and its uncertainties are computed based on the corrected Tb's (from F) and the corrected tie-points (from D), H: the sea ice concentrations are corrected for land-spill-over and gridded into daily 25km EASE-2 grids using the land-mask as input (from I), J: the climatological masks are applied (from K) and flags are applied to each of the daily grid-points, L: is the final sea ice concentration dataset.

## 4. The sea ice concentration and its uncertainty

The sea ice concentration  $(c_{ice})$  in eq. 1 is estimated using the measured brightness temperature  $(T_{p, measured})$  and the open water  $(T_{p, water})$  and ice  $(T_{p, ice})$  tie points, i.e.

$$c_{ice} = \frac{T_{B,measured} - T_{p,water}}{T_{p,ice} - T_{p,water}}$$
(1)

Since the geophysical noise reduction uses the radiative transfer equation, which requires  $c_{ice}$  as input, sea ice concentration is processed iteratively in two steps: 1) the  $c_{ice}$  is estimated using uncorrected TB's and tie-points derived from uncorrected data. The  $c_{ice}$  estimate is truncated to the interval between 0 and 1 and an open water filter is applied forcing all  $c_{ice}$  values less than 0.3 to 0. 2) The  $c_{ice}$  estimate from step (1) is used in the radiative transfer calculation together with ERA5 data for for the geophysical noise reduction of the brightness temperatures and  $c_{ice}$  is then estimated again in a second iteration this time using corrected brightness temperatures and corrected tie-points. The mean values of  $\overline{V}$ ,  $\overline{W}$ ,  $\overline{L}$ ... used in the reference simulation is a weighted average with  $c_{ice}$  of the mean water and ice tie-point values.

These iterations updating  $c_{ice}$  could in principle continue. However, tests show that updates are small after two iterations (e.g. Lavergne et al., 2019).

The total sea ice concentration uncertainty is the combination of two components: 1) the algorithm uncertainty which includes instrument noise and tie-point variability (geophysical noise) and 2) the resampling uncertainty which is uncertainty due to data resampling.

The algorithm uncertainty is the squared sum of the independent components following Parkinson et al. (1987), without the instrument noise term which is included in the two tie-point uncertainties in eq. 2

$$\delta c_{ice, algorithm} = \left( \left( \frac{-(1-c_{ice})\delta T_{p, water}}{T_{p, ice} - T_{p, water}} \right)^2 + \left( \frac{-c_{ice}\delta T_{p, ice}}{T_{p, ice} - T_{p, water}} \right)^2 \right)^{1/2}$$
(2)

where  $\delta T_{B}$  is the brightness temperature error of 3 K (Parkinson et al., 1987),  $\delta T_{p,water}$ , is the water tie-point error, here the (one) standard deviation of the daily tie-point,  $\delta T_{p,ice}$ , is the ice tie-point error here the (one) standard deviation of the daily tie-point. The water and ice tie-point errors are weighted with the sea ice concentration and all three errors are normalized with the ice - water brightness temperature contrast here the 2-weekly tie-points. The algorithm uncertainty is computed on swath data.

The resampling uncertainty,  $\delta c_{ice, resampling}$  is the maximum  $c_{ice}$  - minimum  $c_{ice}$  difference of a 3 x 3 pixel window. The resampling uncertainty is computed on resampled data.

The total uncertainty is the squared sum of the algorithm and the resampling uncertainty in eq. 3, i.e.

$$\delta c_{ice, total} = \sqrt{\delta c_{ice, algorithm}^{2} + \delta c_{ice, resampling}^{2}}$$
(3)

The two uncertainty components and the total uncertainty are provided separately in the data file.

## **5.** The output sea ice concentration dataset

The dataset begins on launch day Dec. 11, 1972 and continues until May 16. 1977, however, there are gaps especially after the summer 1975. There are daily product files unless no data is available for that day.

#### 5.1 The land, coast and climatological masks

The land-mask is based on the ESA CCI land cover project coastline. It is here called the ESA CCI sea ice version 3 landmask.

#### **5.2** The sea-ice concentration and Tb variables

The main variable holding the sea-ice concentration from ESMR is ice\_conc. It contains the fields of SIC on which all filters and thresholds were applied. Variable raw\_ice\_conc\_values holds the original SIC values from the retrieval algorithm, before filters and thresholds are applied.

The product files additionally stores daily gridded ESMR brightness temperatures, both the original (uncorrected) and corrected TBs.

#### 5.3 The processing flags and land-spill over correction

Land-spill\_over correction is following the procedure described in Markus and Cavalieri (2009). The flag number and its meaning is summarized in Table 1.

Flag number	Flag meaning
0	Nominal retrieval by the SIC algorithm
1	Position is over land
2	Position is lake
3	SIC is set to zero by the open water filter
8	SIC value is changed for correcting land spill-over effects
16	Handle with caution, the 2m air temperature is high at this position, and this might be false ice
32	Coast

Table 1: The processing flags applied to each of the data points

64	SIC is set to zero since position is outside maximum sea ice climatology
128	Point not accepted but no other flags raised

## 5.3 Where to get the data?

The data are freely available from the ESA CCI open data portal: <u>https://climate.esa.int/en/odp/#/project/sea-ice</u>

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